Control of Uncertain Systems: Modelling, Approximation, and Design

A workshop on the occasion of Keith Glover's 60th birthday

PROGRAMME

Thursday 20 April 2006					
19:00 -	- 22:00	Reception	Old Library, Pembroke College		
Friday 21 April 2006					
	Lectures will be held in the Fisher Building, St. John's College.				
8:15	Regist	ration desk open. Coffee			
8:55	Welco	me	Vice-Chancellor Alison Richard		
Chair: David Mayne (Imperial College)					
9:00	Brian Anderson (Australian National University)		LMI-Based Gain Scheduling Control Design for a Class of Linear Parameter Varying Systems		
9:30	Pablo Iglesias (The Johns Hopkins University)		Feedback Regulation of Cell Shape During Cytokinesis		
10:00		Dullerud ersity of Illinois)	Model Reduction of Strongly Stable Nonstationary LPV Systems		
break					
Chair: Anders Rantzer (Lund Institute of Technology)					
11:00	-	• Brockett ard University)	Using Time-Varying Feedback to Improve System Identification		
11:30	Harry (The V	Dym Veizmann Institute)	Riccati Inequalities and Reproducing Kernel Hilbert Spaces		
12:00	Hiden (RIKE	ori Kimura N)	Long-Run Behaviours of Genetic Toggle Switch		
lunch					
		<u>Chair:</u> Jonathan Pa	artington (University of Leeds)		
14:00		Curtain rsity of Groningen)	Robust Stabilization with Respect to Coprime Factor Perturbations Revisited		
14:30		el Cantoni ersity of Melbourne)	On the Gap Metric for Finite-dimensional Linear Time-varying Systems in Continuous Time		
15:00		l Gevers ersité Catholique de Louvain)	Experiment Design for Robust Control: Why Do More Work Than Is Needed		
break					
		<u>Chair:</u> Pramod Khar	gonekar (University of Florida)		
16:00	Rick H (Unive	lyde ersity of Bristol)	Review of Multivariable Control Applied to the VAAC Harrier and Remaining Open Questions		
16:30		Vinnicombe rsity of Cambridge)	Fundamental Limitations in Gene Regulation		
17:00	Jan Willems (Katholieke Universiteit Leuven)		State Construction from Measured Data		
19:00 19:30	Pre-di Banqu	nner drinks let	Gonville and Caius College		

Saturday 22 April 2006					
8:30	Coffee				
	Chair: Ian Postlethwaite (University of Leicester)				
9:00	M. Vidyasagar (Tata Consultancy Services)	Stochastic Modelling Over a Finite Alphabet and Algorithms for Finding Genes from Genomes			
9:30	Lino Guzzella (Swiss Federal Institute of Technology)	Past, Present and Future of Automotive Control			
10:00	Andy Packard (University of California, Berkeley)	Collaborative Science: Give Me Your Information, Not Your Conclusions			
break					
Chair: Manfred Morari (Swiss Federal Institute of Technology)					
11:00	Karl Astrom (Lund Institute of Technology)	Qualitative Assessment of Achievable Performance in Loop Shaping Design			
11:30	Nick Collings (University of Cambridge)	IC Engine Control - Enduring Challenges			
12:00	John Doyle (California Institute of Technology)	Robustness and Complexity			
	lu	unch			
Chair: Richard Vinter (Imperial College)					
14:00	Sanjay Lall (Stanford University)	Optimal Control Subject to Decentralization Constraints			
14:30	David Limebeer (Imperial College)	An H∞ Loop-Shaping Approach to Steering Control for High-Performance Motorcycles			
15:00	George Papageorgiou (Honeywell Laboratories)	Distance Measures, Robust Stability Conditions, and Robust Performance Guarantees for Uncertain Systems			
	b	reak			
Chair: Tryphon Georgiou (University of Minnesota)					
16:00	Gary Balas (University of Minnesota)	Control of High-Speed Underwater Vehicles			
16:30	Bruce Francis (University of Toronto)	Getting Mobile Autonomous Robots to Rendezvous			

17:00-18:00 Reception