Optimal Beer Fermentation

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ABSTRACT

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A new tool was developed to solve a wide range of optimal beer fermentation problems. Using a mathematical model of beer fermentation, the direct dynamic optimization technique of sequential quadratic programming was investigated for determining the optimal cooling policy to maximize ethanol production for a fixed final time, including effects that optimize flavor. The new tool is very efficient for determining optimal cooling strategies. New control strategies were found that increase ethanol production while decreasing the deleterious effects of fusel alcohols and keeping the acetaldehyde concentrations at moderate levels. Model parameter sensitivity was investigated and it was shown that the system could be regulated successfully around optimal temperature profiles.

Key words: Dynamic optimization, fermentation, mathematical modeling, optimal flavor.

Introduction

It is common in industrial beer fermentation to use a cooling refrigeration system to control the temperature of the batch beer fermentation process. Gee and Ramirez¹¹ have computed optimal cooling strategies using the indirect method of the calculus of variations. They derived and solved the necessary conditions for the optimal control problem of maximizing ethanol concentration in minimum time. The model they used was a basic growth model based upon the work of Engasser et al.8 Gee and Ramirez¹² have also developed a complete flavor model which starts with their growth model and adds a nutrient model and a model for desirable and undesirable flavor species. Other models have also appeared since then. Garcia et al.⁹ present a fusel alcohol model, Garcia et al.¹⁰ developed a neural network model for ethyl caproate, de Andres-Toro et al.⁶ developed a three component biomass model that includes lag phase, active cell and dead cell components. Titica et al.²² present a flavor model based upon prior biological information and an analysis of experimental data, and Trelea et al.^{23,24} developed models based on biological knowledge, empirical data and artificial neural networks. With limited data they conclude

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that the fundamental models were superior. Since the time of the work of Gee and Ramirez^{11,12} new and powerful direct dynamic optimization techniques have been developed. This coupled with vast increases in computational power and speed means that direct methods are now being investigated for developing new optimal control strategies. De Andres-Toro et al.⁵ used genetic algorithms to optimize for aroma targets in minimum time. Trelea et al.²⁴ used a variant of sequential quadratic programming to optimize flavor components in minimum time. They used a model based mostly upon empirical data for their work. In this work we will use a modified version of the fundamental model of Gee and Ramirez¹² and sequential quadratic programming to create a new tool capable of solving optimal brewing problems such as maximizing alcohol, while also optimizing flavor components.

Sequential quadratic programming is known to be a very effective and efficient means of optimization of systems with constraints. The main draw back is that it tends to converge to local rather than global optima. If a good initial guess is available then this method is an excellent choice for direct dynamic optimization. Sequential quadratic programming has been used to solve nonlinear optimization problems with both linear and nonlinear constraints. The basis of the technique is that the nonlinear objective function is expanded in a Taylor Series to get an approximate quadratic objective function. The nonlinear constraints are linearized. Now the problem is in a standard form for quadratic programming which solves the necessary conditions for a constrained extrema using a standard linear programming program. The results of this are used as the starting point for the next approximate quadratic objective function and linearized constraints¹³. It is important to have good initial guesses for developing the approximate quadratic objective function and linearized constraints. Otherwise local optima are to be expected. Schittkowski et al.¹⁷ compared a number of opti-mization methods including sequential quadratic programming, while Dontchev et al.7 established convergence results for sequential quadratic programming. Numerous applications of the technique have appeared including that of Hartig and Keil¹⁴ on optimization of fixed bed reactors, Hartig et al.¹⁵ on fed batch reactors, Wang and Shyu²⁵ on fed batch fermentation for ethanol production, Shukla and Pushpavanam¹⁸ on fed batch bioreactors, Rohani et al.¹⁶ on crystallization processes, Takeda and Ray²⁰ on polyolefin reactors, Chae et al.³ on fed batch recombinant protein expression, Tada et al.¹⁹ on L-lysine production, Tian et al.²¹ on batch emulsion copolymerization, Ahari et al.¹ on radial flow reactors, and Costa et al.⁵ on crystallization processes.

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A Beer Flavor Model

The batch beer fermentation flavor model that will be used in this work is based on the model of Gee and Ramirez¹²:

Growth model

Three basic sugars are considered for consumption

Glucose
$$\frac{dG}{dt} = -\mu_1 X \tag{1}$$

Maltose

Maltose
$$\frac{dM}{dt} = -\mu_2 X$$
 (2)
Maltotriose $\frac{dN}{dt} = -\mu_3 X$ (3)

The specific growth rates are given below and show that the maltose specific growth rate is inhibited by glucose, and that maltotriose is inhibited by both glucose and maltose:

dt

$$\mu_{1} = \frac{\mu_{G}G}{K_{G} + G} \qquad \mu_{2} = \frac{\mu_{M}M}{K_{M} + M} \frac{K'_{G}}{K'_{G} + G}$$

$$\mu_{3} = \frac{\mu_{N}N}{K_{N} + N} \frac{K'_{G}}{K'_{G} + G} \frac{K'_{M}}{K'_{M} + M}$$
(4)

The temperature dependency of these specific growth rates are

$$\mu_{i} = \mu_{i0} \exp\left(-\frac{E_{\mu i}}{RT}\right), \quad i = G, M, N$$

$$K_{i} = K_{i0} \exp\left(-\frac{E_{Ki}}{RT}\right), \quad i = G, M, N \quad (5)$$

$$K_{i}' = K_{i0}' \exp\left(-\frac{E_{Ki}'}{RT}\right), \quad i = G, M$$

The biomass production rate includes an inhibition term in the biomass concentration as discussed by Gee and Ramirez¹²:

$$\frac{dX}{dt} = \mu_X X \tag{6}$$

where

$$\mu_X = (Y_{XG}\mu_1 + Y_{XM}\mu_2 + Y_{XN}\mu_3) \frac{K_X}{K_X + (X - X_0)^2}$$
(7)

The ethanol production is assumed to be proportional to the amount of sugar consumed

$$E = E_0 + Y_{EG}(G_0 - G) + Y_{EM}(M_0 - M) + Y_{EN}(N_0 - N)$$
(8)

The batch temperature (T) is given by an energy balance which includes the heat of reaction effects and the cooling capacity which is a control on the process.

$$\frac{dT}{dt} = \frac{1}{\rho c_p} \left(\Delta H_{FG} \frac{dG}{dt} + \Delta H_{FM} \frac{dM}{dt} + \Delta H_{FN} \frac{dN}{dt} - u(T - T_c) \right)$$
(9)

326 JOURNAL OF THE INSTITUTE OF BREWING Here *u* is the control variable of the cooling rate per volume per degree, and T_c is the coolant temperature.

Nutrient model

(2)

Amino acids have been shown to affect the formation of flavor compounds². Therefore, a specific nutrient model is used for the amino acids of leucine (L), isoleucine (I) and valine (V). The amino acid assimilation is assumed to be negatively proportional to the growth rate, limited by the availability of the amino acid in the media and with a lag phase at the beginning of fermentation.

$$\frac{dL}{dt} = -Y_{LX} \frac{dX}{dt} \frac{L}{K_L + L} D$$

$$\frac{dI}{dt} = -Y_{IX} \frac{dX}{dt} \frac{I}{K_I + I} D$$

$$\frac{dV}{dt} = -Y_{VX} \frac{dX}{dt} \frac{V}{K_V + V} D$$
(10)

where the lag effect is given by

$$D = 1 - e^{-t/\tau_d}$$
(11)

Flavor model

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Four main categories of flavor compounds are considered. These are fusel alcohols which should be minimized, esters which should be present in high concentrations, vicinal diketones which should not be present in too high a concentration and acetaldehyde which should also be kept in moderate concentrations.

Fusel alcohols. Fusel alcohols are undesirable species since they contribute a plastic, solvent like flavor and are a strong contributor to symptoms comprising a hangover. The model assumes an enzymatic production based upon the appropriate amino acid concentration¹². The fusel alcohols considered are isobutyl alcohol (IB), isoamyl alcohol (IA), 2-methyl-1-butanol (MB), and propanol (P).

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$$\frac{dIB}{dt} = Y_{IB}\mu_V X \qquad \frac{dIA}{dt} = Y_{IA}\mu_L X$$

$$\frac{dMB}{dt} = Y_{MB}\mu_I X \qquad \frac{dP}{dt} = Y_{PE}(\mu_V + \mu_I) X$$
(12)

Esters. Esters are desirable flavor compounds since they contribute a great deal to beer aroma and add a full bodied character to beer. Three esters are considered in the model and they are ethyl acetate (EA), ethyl caproate (EC) and isoamyl acetate (IAc). They are modeled as proportional to either amino acid consumption rates or growth rate or sugar consumption rates.

$$\frac{dEA}{dt} = Y_{EA}(\mu_1 + \mu_2 + \mu_3)X$$

$$\frac{dEC}{dt} = Y_{EC}\mu_X X \qquad \frac{dIAc}{dt} = Y_{IAC}\mu_{IA}X$$
(13)

Vicinal diketones. Vicinal diketones (VDK) are considered undesirable flavor compounds in high concentrations. They add a buttery flavor to beer. All vicinal diketones are lumped together as one flavor species and are assumed to be produced proportional to the growth rate and consumed proportional to their own concentration.

$$\frac{dVDK}{dt} = Y_{VDK}\mu_X X - k_{VDK}VDK X$$
(14)

Acetaldehyde. Acetaldehyde (AAI) exhibits similar dynamics to that of VDK in that it is produced early in the fermentation and then consumed later in the fermentation. Acetaldehyde contributes a grassy flavor to beer and high concentrations are not desirable.

$$\frac{dAAl}{dt} = Y_{AAl}(\mu_1 + \mu_2 + \mu_3)X - k_{AAl}AAlX$$
(15)

Problem Statement

Since the sequential quadratic programming algorithm is a function optimization rather than a dynamic functional optimization, the dynamic model must first be placed in discrete form. This can be accomplished by a simple first order finite difference approximation

$$\dot{\mathbf{x}} = \mathbf{f}(\mathbf{x}, \mathbf{u}) \text{ becomes} \mathbf{x}(i+1) = \mathbf{x}(i) + \mathbf{f}(\mathbf{x}(i), \mathbf{u}(i))\Delta t$$
(16)

The discrete version of the problem can now use sequential quadratic programming to find the optimal set of controls $\mathbf{u}(i)$ that will extremize a particular objective function.

An appropriate objective function needs to be formulated to reflect the objectives of the investigation. The growth objective function is just to maximize the ethanol concentration at the final time. This is given by the equation,

$$J = E(t_f) \tag{17}$$

Optimal Control Using a Growth Model

Gee and Ramirez¹¹ used the calculus of variations to determine the optimal temperature policy that maximizes ethanol production with a maximum temperature state constraint that tends to characterize the flavor of the beer. There are also minimum and maximum constraints on the control variable of the cooling capacity. Gee and Ramirez¹¹ found that the optimal control policy is a bang-bang policy to bring the temperature up or down to the maximum temperature followed by control along a singular arc of constant maximum temperature. They also discovered that a well tuned PI controller could give almost as good a result in terms of maximum alcohol as the optimal control scheme. The model for this problem is given by Equations 1–9.

First we investigate whether the discrete version of the model approximates the continuous model well. We investigated several time increments and found that dividing the continuous time domain into 30 subintervals worked well.

Next, the use of the sequential quadratic programming to solve the discrete optimal control policy was investigated. An upper constraint on the cooling capacity of 40 KJ/hr cu m K and a lower bound of zero was used. The nonlinear inequality constraint that the system temperature must be less than or equal to a maximum temperature was employed. The nonlinear objective function is to maximize the ethanol concentration at the final time (Equation 17). The program worked extremely well converging in 39 iterations from an initial guess of the control policy of the PI controller. The computational time on an IBM ThinkPad T40 was 2.67 seconds. The optimal ethanol concentration was 727.3 g mole/cu m compared to a value of 715.9 for the PI controller. This small 1.6% increase was expected based upon the results of Gee and Ramirez¹¹. The PI and optimal cooling profiles are given in Fig. 1. They correspond to the results of Gee and Ramirez¹¹. The PI and optimal profiles are similar but certainly have some significant differences in that the move from zero cooling occurs at different times and the optimal controller stays on the singular arc of the upper bound of the maximum temperature once the cooling leaves its zero value. The optimal control found by this very efficient method is a bang-bang policy followed by control on



Fig. 1. Optimal and PI control strategies using the growth model and a maximum temperature constraint.



Fig. 2. Optimal temperature profile to maximize ethanol.

the singular arc. For this problem the optimal system is always on a constraint boundary using sequential quadratic programming of either the lower bound for the cooling or the nonlinear inequality constraint of a maximum system temperature.

The optimal temperature profile that maximizes ethanol is given in Fig. 2 and shows that while the control is at its minimum value the temperature rises at its maximum rate, but that once the maximum temperature (12°C) was reached, it stayed on this singular arc.

Optimal Flavor Control

The flavor components were then added to the mathematical model. Gee and Ramirez¹² report kinetic and yield parameters obtained from nonlinear curve fits for temperatures of 10.5°C, 12°C and 14.5°C. All the yield parameters were averaged over these three temperatures but explicit temperature effects were included for the kinetic rate constants. Based upon Arrhenius plots, frequency factors and activation energies were obtained through linear regression. All parameters were reasonable except for the

Table I. List of terms.

Parameter	Value	Units
$\ln \mu_{G0}$	35.77	ln h ⁻¹
$\ln \mu_{M0}$	16.4	ln h ⁻¹
$\ln \mu_{N0}$	10.59	ln h ⁻¹
E_{G0}	22.6	kcal/gmole
E_{M0}	11.3	kcal/gmole
E_{N0}	7.16	kcal/gmole
$\ln K_{G0}$	-121.3	ln gmole/cu m
$\ln K_{M0}$	-19.5	ln gmole/cu m
$\ln K_{N0}$	-26.78	ln gmole/cu m
E_{KG}	-68.6	kcal/gmole
E_{KM}	-14.4	kcal/gmole
E_{KN}	-19.9	kcal/gmole
$\ln E'_{G0}$	23.33	ln gmole/cu m
$\ln E'_{M0}$	55.61	ln gmole/cu m
E'_{KG}	10.2	kcal/gmole
E'_{KM}	26.3	kcal/gmole
Y_{XG}	0.134	
Y_{XM}	0.268	
Y_{XN}	0.402	
ΔH_{FG}	-91.2	kJ/gmole
ΔH_{FM}	-226.3	kJ/gmole
ΔH_{FN}	-361.3	kJ/gmole
Y_{LX}	0.0832	
Y_{IX}	0.0363	
Y_{VX}	0.0273	
K_I	0.365	gmole/cu m
$\ln K_{L0}$	10.14	ln gmole/cu m
$\ln K_{V0}$	328	ln gmole/cu m
E_{KL}	5.95	kcal/gmole
E_{KV}	211.9	kcal/gmole
τ_d	23.54	h
Y_{IB}	0.203	
Y_{IA}	0.557	
Y_{MB}	0.472	
Y_P	0.235	
Y_{EA}	0.000992	
Y_{EC}	0.000118	
Y _{IAc}	0.0269	
Y_{VDK}	0.000105	
Y _{AAl}	0.01	
$\ln k_{VDK}^{\circ}$	86.8	ln cu m/(h gmole)
$\ln k_{AAl}^0$	10.4	ln cu m/(h gmole)
E_{VDK}	54.3	kcal/gmole
E_{AAl}	11.1	kcal/gmole

isoleucine correlation which showed a slight wrong direction temperature effect. The isoleucine kinetic data were therefore averaged and an averaged rate constant was assumed to apply over the temperature range. The flavor kinetic constants, as well as growth constants used in this study, are given in Table I.

The next goal was to include flavor aspects to maximize an objective function that maximizes ethanol production, but does not increase the fusel alcohol concentrations over the previous case with a low maximum temperature constraint of 12°C. Keeping fusel alcohols low was deemed very important to the taste of the beer, as well as to the health of the consumer. A secondary concern was to increase the ester concentration if possible. A new objective function was proposed, which was to be maximized:

$$U = E(t_{f}) - C[IB(t_{f}) + IA(t_{f}) + MB(t_{f}) + P(t_{f})]$$
(18)

Here the weighting factor C reflects the relative importance of maximizing the final ethanol concentration to that of minimizing the sum of the fusel alcohol concentrations at the final time. For the base case, shown in Figs. 1 and 2, the final ethanol concentration was 727.3 gmole/cu m and the sum of the fusel alcohols was 1.507 gmole/cu m. For the two effects to be of equal importance the weighting factor C needs to be about 500.

Again the sequential quadratic programming approach was used but with a relaxation of the maximum temperature inequality constraint, to be 15°C, which is the upper range value of temperature used to determine the kinetic parameters used in this study. Several different values of *C* were tried and a value of 900 showed a good compromise between the two effects in the objective function. The optimization from the control profile found from using PI control around a set point of 12°C was started. The optimal results are given in Fig. 3 for the optimal cooling rate and Fig. 4 for the optimal temperature profile. These optimal conditions resulted in a final ethanol concentration of 762.2 gmole/cu m which is a 4.8% improvement over the optimal growth value. The new optimal fusel alcohol concentrations sum to 1.505 which is slightly



Fig. 3. Optimal cooling rates for an optimal flavor objective.

lower than the growth value of 1.507. Therefore additional alcohol was produced, while lowering the fusel alcohol concentration. This is a very important practical result. The problem took 136 iterations to converge and a computational time of 8.4 seconds on an IBM ThinkPad T40. If the value of *C* is too low, then the optimal growth model results are obtained of an initial period of no cooling followed by regulation at the maximum temperature. This does result in an increase in the fusel alcohol concentration of 1.7%. If the value of *C* is too high then the fusel alcohol production (40% reduction) and the system temperature goes slowly down to very low values of 4.7°C.

The optimal flavor cooling policy shows that one starts cooling the system at the early times in order to keep a slow steady rate of rise of temperature and the fermentation rate. At later times the cooling capacity is lowered, allowing the temperature to continue to slowly rise. At the very end of the cycle, the cooling rate is significantly increased approaching its maximum value.



Fig. 4. Optimal temperature profile using an optimal flavor objective.



Fig. 6. Optimal ethanol production using an optimal flavor objective.

The optimal temperature profile is given in Fig. 4. It shows a gentle almost linear rise, reaching the maximum near the end of the fermentation process. Significant cooling is now required to keep the temperature at or below its maximum value. These optimal conditions are significantly different from those based solely upon the growth model which shows a rapid rise in temperature and fermentation rate until the maximum temperature is reached and then regulation at that maximum temperature. The insights obtained here offer real promise for developing new control schemes that can increase alcohol production while minimizing fusel alcohol production.

In addition, these optimal conditions resulted in an increase in ester production from 0.2379 gmole/cu m to 0.2479 gmole/cu m. This is an increase of 3.8% in the production of flavor enhancing esters. It seems that in maximizing ethanol one also maximizes ester production.

Fig. 5 gives the optimal sugar consumption profile, Fig. 6 the optimal ethanol production profile, Fig. 7 the optimal amino acid consumption profile, Fig. 8 the opti-



Fig. 5. Optimal sugar consumption using an optimal flavor objective.



Fig. 7. Optimal amino acid profiles using an optimal flavor objective.

mal fusel alcohol profile, Fig. 9 the optimal ester profile, Fig. 10 the optimal VDK profile and Fig. 11 the optimal acetaldehyde profile.

The only draw back with this strategy was that the acetaldehyde final concentration actually increased by 7.6% and this could give the beer too grassy a flavor. However, the VDK concentration was reduced by 42.7%, which would tend to mitigate the acetaldehyde increase, although the VDK concentrations are much lower than that of acetaldehyde (see Figs. 10 and 11). In order to reduce the final acetaldehyde concentration a new objective function was used:

$$J = E(t_f) - C_1[IB(t_f) + IA(t_f) + MB(t_f) + P(t_f)]$$

- C_2AAl(t_f) (19)

Using values of C_1 of 810 and C_2 of 610 the optimal cooling capacity shown in Fig. 12 and the optimal system temperature profile of Fig. 13 was obtained. The problem converged in 54 iterations with a computational time of

10.1 seconds. The optimal results have an increase in the final ethanol concentration of 6.2%, an increase in the final ester concentration of 4.6%, a fusel alcohol concentration that stays the same, a decrease in the final VDK concentration of 26.7% and a slight increase in the final acetaldehyde concentration of 1.27%. The optimal temperature policy shows a steady initial rise in temperature near its maximum rate, using some cooling to modify these early rates of change. Once a temperature of 13° C was reached, the cooling increased in order to raise the temperature gradually to around 13.5° C. Again the optimal control approach has been able to develop a new operational strategy that is a significant improvement over the conventional optimal growth policy.

The values of C_1 and C_2 can significantly change the results. When they are low, the optimal growth policy is obtained which results in excess production of fusel alcohols (1.7%) and acetaldehyde (2.3%). When they are too large, the system is excessively cooled resulting in a 40% reduction in ethanol production.



Fig. 8. Optimal fusel alcohol profiles using an optimal flavor objective.



Fig. 10. Optimal VDK profile using an optimal flavor objective.



Fig. 9. Optimal ester profiles using an optimal flavor objective.



Fig. 11. Optimal acetaldehyde profile using an optimal flavor objective.

Implementation

The regulation of the system using a tracking PI controller about the optimal temperature profile was investigated. A velocity mode for the PI algorithm was used,

$$u(k) = u(k-1) + KI \,\Delta t \, e(k) + KP \,\Delta t \left(e(k) - e(k-1)\right) \quad (20)$$

Here k denotes the time index, Δt the time interval, KI the integral gain and KP the proportional gain. The tracking error, e(k) is given by

$$e(k) = T(k) - T_{\text{optimal}}(k)$$
(21)

where $T_{\text{optimal}}(k)$ is the optimal value of the temperature at any time t(k).

Fig. 14 shows that a tracking regulator can follow the optimal temperature profile well with KP = 40 and KI = 5. The final ethanol concentration was within 0.3% of the optimal value, the fusel alcohol concentration within 0.1% and the acetaldehyde concentration within 0.1% of the optimal value. The esters and VDK concentrations were



Fig. 12. Optimal cooling including acetaldehyde minimization.



Fig. 13. Optimal temperature policy including acetaldehyde minimization.

the same as with the optimal conditions. These results showed that the optimal flavor results can easily be implemented with simple feedback controllers.

The effect of model uncertainty was also investigated. One of the least well known parameters is that of the acetaldehyde consumption rate constant k_{AAl} In order to investigate this, the natural log of the frequency factor ln k_{AAl}^0 was increased by 10%. This resulted in a significantly lower final concentration of acetaldehyde of 0.218 gmole/ cu m. The optimal temperature profile for this case was essentially that of Fig. 13 so that regulating about that profile still resulted in beer with optimal flavor. The maltose activation energy was also lowered, from 11.3 kcal/ gmole to 10.93 kcal/gmole, which consumes significantly more maltose than the base case. This raised the optimal growth final ethanol concentration to 967.7 gmole/cu m. The optimal flavor temperature profile was however essentially that of Fig. 13 and regulating about that profile gives essentially the same result as an optimal profile based upon Equation 19. This shows that the optimal temperature profile of Fig. 13 was quite insensitive to model uncertainty and could be used for beers that approximately follow the model parameters of this study. The optimal temperature profile seems to more a function of the model structure than specific model parameters.

As part of the investigation of the robustness of the optimal temperature profile, a slightly different optimization objective function was considered.

$$J = -C \left(\frac{E(t_{f})}{0.1E_{\text{nom}}(t_{f})}\right)^{2} + \left(\frac{IB(t_{f})}{0.1IB_{\text{nom}}(t_{f})}\right)^{2} + \left(\frac{IA(t_{f})}{0.1IA_{\text{nom}}(t_{f})}\right)^{2} + \left(\frac{MB(t_{f})}{0.1MB_{\text{nom}}(t_{f})}\right)^{2} + \left(\frac{P(t_{f})}{0.1P_{\text{nom}}(t_{f})}\right)^{2} + \left(\frac{AAl(t_{f})}{0.1AAl_{\text{nom}}(t_{f})}\right)^{2}$$
(22)

Again, the goal was to try to maximize the final ethanol concentration while minimizing the fusel alcohol and acetaldehyde concentration. Each concentration was normal-



Fig. 14. Temperature regulation about the optimal temperature profile.

ized about a variation (10%) in a nominal concentration for that species. The nominal values were chosen as the final concentrations of the base case of optimal growth control with an upper bound of 12°C. The optimal solutions using this objective function behaved similarly to those with the initial objective function of Equation 19. The solution was sensitive to the value of the weighting factor C in Equation 22. For a value of C = 2.7 the optimal solution was quite similar to that presented earlier with an optimal temperature profile approximately that of Fig. 13. When C was too low one attempts to find solutions that tend to low temperatures and when it was too high one tends to the optimal growth solution, just as was found with the previous objective function. The similarity of the results using slightly different objective function formulations points out the uniqueness of the optimal strategy to produce high alcohol beers with optimal flavor.

Conclusions

A new efficient optimization tool to develop optimal cooling profiles for batch beer fermentation has been presented. This general tool has been used to first develop optimal strategies that optimize ethanol production only. This results in a strategy that heats the system at its maximum capacity and then regulates along a maximum temperature constraint (12°C) that is some measure of product quality. This is the classical approach taken by brewers. By including the desire to minimize the deleterious effects of fusel alcohols, as well as maximizing ethanol production, a new control profile was developed that gently raises the temperature to a maximum feasible temperature and then regulates along that temperature for a short period of time. The maximum feasible temperature (15°C) was significantly higher than the temperature constraint value that is a measure of product quality. This objective resulted in a 4.8% increase in alcohol production with a slightly lower production of fusel alcohols. The only drawback to this policy was that the final acetaldehyde concentration was increased by 7.6%. Other flavor compounds were improved. A new objective was therefore developed that included the desire to minimize the production of acetaldehyde. The optimal control policy for this objective was a more rapid rise in temperature to a value of 13°C and then a slow rise to a final temperature of 13.5°C. This strategy resulted in a 6.7% increase in alcohol production with the same fusel alcohol final concentration and only a 1.3% increase in the final acetaldehyde concentration. All other flavor compounds were improved. These results show the power and importance of developing optimal control policies for beer fermentation based upon this optimization tool. In addition it was shown that a simple tracking proportional-integral controller can be used to follow optimal temperature profiles and that the optimal results are not that sensitive to model uncertainty.

This paper has demonstrated how the new optimization tool was useful for one product improvement application. Other product improvement applications are also possible such as reducing fusel alcohols with out impacting ester production or increasing esters without impacting the final acetaldehyde concentration. Improved productivity applications are also possible, such as producing a similar quality beer in less time. Batch to batch consistency issues can also be addressed, such as the production of a consistent beer profile with variable initial conditions such as a higher initial temperature or a lower inoculum levels. The tool is also useful for flavor matching in going to a new or different plant production facility. Model parameters would be determined for each plant and the optimization tool used to determine temperature control strategies that maintain product quality between the plants.

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